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Co-Designing a System for Regional Weather Prediction

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O Can you spot the weather model?

Data set: 11.8.2014 00.00:00 UTC - 13.8.2014 23.57:30 UTC

Spatial resolution (temporal resolution): Model: 1.1 km (2.5'), satellite: approx. 4-5km (5'), weather radar: approx. 1km (5')

Simulations: Dr. Oliver Fuhrer (MeteoSwiss)

Model computing: Cray XK7 (GPU/CPU hybrid supercomputing system), Swiss National Supercomputing Centre CSCS

Visualization, data processing: Dr. Oliver Stebler, Dr. Urs Beyerle

Background data: Reto Stöckli, NASA Earth Observatory (NASA Goddard Space Flight Center)

Visualization project lead: Dr. Oliver Stebler (oliver.stebler@env.ethz.ch)

Supervision: Prof. Dr. Reto Knutti

Version: 23.1.2015



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Current operational system

ECMWF-Model

16 km gridspacing2 x per day 10 day forecast

COSMO-7

 $\Delta x = 6.6$ km, $\Delta t = 60$ s 393 x 338 x 60 cells 3 x per day 72 h forecast

COSMO-2

 $\Delta x = 2.2$ km, $\Delta t = 20$ s 520 x 350 x 60 cells 7 x per day 33 h forecast 1 x per day 45 h forecast



Next-generation system



Ensemble data assimilation: LETKF

Benefit of high resolution

(18-days for July 9 - 27, 2006)



Benefit of ensemble

0

(heavy thunderstorms July 24, 2015)



Benefit of ensemble

0

(heavy thunderstorms July 24, 2015)



Computational cost = 40 X

(relative to current operational system)

0



Production with COSMO @ CSCS

Cray XE6 (Albis/Lema)

MeteoSwiss operational system Since ~4 years

Next-generation system

Accounting for Moore's law (factor 4)





Co-design: A way out?

Potential

- Time-to-solution driven
- Exclusive usage
- Only one critical application
- Stable configuration (code and system)
- Current code is not optimal
- Novel hardware
 architectures

Challenges

- Community code
 - Large user base
 - Performance portability
 - Knowhow transfer
- Complex workflow
- High reliability
- Rapidly evolving technology (hardware and software)

Co-design: Approach

- Design software, workflow and hardware with the following principles
 - Portability to other users (and hardware)
 - Achieve time-to-solution
 - Optimize energy (and space) requirements
- Collaborative effort between
 - MeteoSwiss, C2SM/ETH, CSCS for software since 2010
 - Cray and NVIDIA for new machine since 2013
 - Domain scientists and computer scientists
- Additional funding from the HPCN Strategy (HP2C, PASC)



OpenACC vs. STELLA

• Comparison using hor. diffusion and vert. advection

	runtime	occupancy	DRAM read	throughput write	shared memory	register usage	
non-block	(naive)						
K20X	0.53 ms	0.266	>75.1 GB/s	>35.5 GB/s	0 B	47-53	
K20	0.68 ms	0.285	>39.1 GB/s	>26.3 GB/s	0 B	37-44	
blocked K20X	0.90 ms	0.283	13.9 GB/s	62.9 GB/s	0 B	73	
K20	0.69 ms	0.591	12.7 GB/s	63.1 GB/s	4 B	46	
shared K20	0.54 ms	0.600	15.9 GB/s	16.1 GB/s	4.272 KB	39	
shared-3E K20) 0.56 ms	0.670	15.4 GB/s	16.1 GB/s	4.272 KB	34	
STELLA K20X	0.29 ms	0.90	Conclusions				
K20	0.35 ms	0.90	• STELLA implementation is 1.5 – 2.0 x faster				
			• OpenAc	ance portable	, many ma	nual opt	

σ New MeteoSwiss HPC system

MDS/MG

Hvdra BLANH BLAN

Piz Kesch (Cray CS Storm)

- Installed at CSCS in July 2015 •
- Public announcement today •
- It is now possible to compare our choice against a more "traditional" choice (e.g. Cray XC40 with Haswell CPUs)
 - Fully redundant (failover for • research and development)

New MeteoSwiss HPC system



Piz Dora (Cray XC40)

- "Traditional" CPU based system
- Compute nodes with 2 Intel Xeon E5-2690 v3 (Haswell)
- Pure compute rack
 - Rack has 192 compute nodes
- Very high density (supercomputing line)

Energy Measurement

- We use power clamp for comparison
- Measurements from PMDB and RUR were within 1% of clamp

Piz Dora (Cray XC40)

Power clamp

(external measurement which measures wall consumption including AC/DC conversion, interconnect, but excluding blower)

- 1-2 nodes were down and could not be used (considered in computation)
- **PMDB** (1 Hz, per node)
- **RUR** (total per job)

Piz Kesch (Cray CS Storm)

Power clamp

(external measurement which measures wall consumption including AC/DC conversion, interconnect, but excluding blower)

 Other components (mgmt nodes, extra service nodes, drives) powered down

O Benchmark

COSMO-E

2.2 km gridspacing582 x 390 x 60 gridpoints120 h forecast



Details

- Planned operational setup by MeteoSwiss
- Required time-to-solution = 2h (333 ms per timestep)
- Fill a full rack with members (keeping sockets per member constant)
- COSMO v5.0 (with additions for GPU porting and C++ dynamical core)
- Single precision (both CPU and GPU not fully optimized)

Results	Note Not sure if this is an apples- to-apples comparison, due to different "character" of systems		
	Piz Dora	Piz Kesch	Factor
Sockets at required time-to-solution	~16 CPUs	~7 GPUs	2.4 x
Energy per member	6.19 kWh	2.06 kWh	3.0 x
Time with 8 sockets per member	13550 s	5980 s	2.3 x
Cabinets required to run ensemble at required time-to-solution	0.87	0.39	2.2 x

Results Relative to "Old" Code

0

("Old" = no C++ dycore, double precision)

	Piz Dora	Piz Kesch	Factor
Sockets at required time- to-solution	~26 CPUs	~7 GPUs	3.7 x
Energy per member	10.0 kWh	2.06 kWh	4.8 x
Time with 8 sockets per member	23075 s	5980 s	3.8 x
Cabinets required to run ensemble at required time-to-solution	1.4	0.39	3.6 x

Image: Cray

"Managment summary"

Key ingredients

J

- Processor performance (Moore's law)
- Port to accelerators (GPUs)
- Code improvement
- Increase utilization of system
- Increase in number of sockets
- Target system architecture to application

Note Separating hardware investments from software and workflow investments does not make sense! ~1.7 x ~2.8 x ~1.3 x

~2.8 x

~2.3 x







- New forecasting system doubling resolution of deterministic forecast and introducing a convection permitting ensemble
- Co-design (simultaneous code, hardware and workflow redesign) allowed MeteoSwiss to increase computational load by 40x within 4–5 years
- Operations on a CS Storm system with fat GPU nodes starting Q2 2016
- Energy to solution is a factor 3x smaller as compared to a "tradiational" CPU-based system



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